



WIKIPEDIA
The Free Encyclopedia

Navigation

[Main page](#)
[Contents](#)
[Featured content](#)
[Current events](#)
[Random article](#)
[Donate to Wikipedia](#)

Interaction

[Help](#)
[About Wikipedia](#)
[Community portal](#)
[Recent changes](#)
[Contact Wikipedia](#)

Toolbox

[What links here](#)
[Related changes](#)
[Upload file](#)
[Special pages](#)
[Permanent link](#)
[Cite this page](#)
[Rate this page](#)

Print/export

[Create a book](#)
[Download as PDF](#)
[Printable version](#)

Languages

[Català](#)
[Česky](#)
[Dansk](#)
[Deutsch](#)
[Eesti](#)
[Español](#)

[Français](#)

Article [Discussion](#)

Read [Edit](#)



Switched-mode power supply

From Wikipedia, the free encyclopedia

For other uses, see [Switch \(disambiguation\)](#).

A **switched-mode power supply** (**switching-mode power supply**, **SMPS**, or simply **switcher**) is an electronic [power supply](#) that incorporates a switching regulator in order to be highly efficient in the conversion of electrical power. Like other types of power supplies, an SMPS transfers power from a source like the electrical [power grid](#) to a load (e.g., a personal computer) while converting [voltage](#) and [current](#) characteristics. An SMPS is usually employed to efficiently provide a regulated output voltage, typically at a level different from the input voltage. Unlike a linear power supply, the pass transistor of a switching mode supply switches very quickly (typically between 50 kHz and 1 MHz) between full-on and full-off states, which minimizes wasted energy. Voltage regulation is provided by varying the ratio of on to off time. In contrast, a linear power supply must dissipate the excess voltage to regulate the output. This higher efficiency is the chief advantage of a switched-mode power supply.

Switching regulators are used as replacements for the linear regulators when higher efficiency, smaller size or lighter weight are required. They are, however, more complicated, their switching currents can cause electrical noise problems if not carefully suppressed, and simple designs may have a poor [power factor](#).

Contents [hide]

- Explanation
- Advantages and disadvantages
 - Classification
- SMPS and linear power supply comparison
- Theory of operation
 - Input rectifier stage
 - Inverter stage
 - Voltage converter and output rectifier
 - Regulation
- Transformer design
 - Transformer size
 - Core loss



Interior view of an [ATX SMPS](#): below
 A: input EMI filtering; A: bridge rectifier;
 B: input filter capacitors;
 Between B and C: primary side heat sink;
 C: transformer;
 Between C and D: secondary side heat sink;
 D: output filter coil;
 E: output filter capacitors.
 The coil and large yellow capacitor below E are additional input filtering components that are mounted directly on the power input connector and are not part of the main circuit board.



An adjustable switched-mode power supply for laboratory use

Lëtzebuergesch
Magyar

Nederlands
日本語
Polski
Português
Русский
Slovenčina
Српски / Srpski
Suomi
Svenska
中文

5.3 Copper loss

6 Power factor

7 Types

7.1 Non-isolated topologies

7.2 Isolated topologies

7.3 Quasi-resonant zero-current/zero-voltage switch

8 Efficiency and EMI

9 Failure modes

10 Precautions

11 Applications

12 Terminology

13 See also

14 Notes

15 References

16 External links

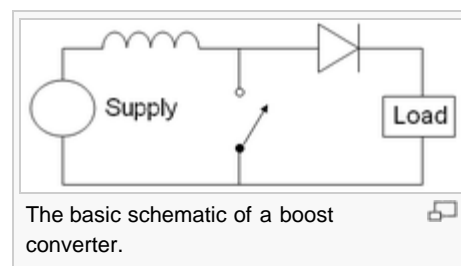
Explanation

[[edit](#)]

A **linear regulator** provides the desired output **voltage** by dissipating excess power in **ohmic losses** (e.g., in a resistor or in the collector–emitter region of a pass transistor in its active mode). A linear regulator regulates either output voltage or current by dissipating the excess electric power in the form of **heat**, and hence its maximum power efficiency is voltage-out/voltage-in since the volt difference is wasted. In contrast, a switched-mode power supply regulates either output voltage or current by switching ideal storage elements, like **inductors** and **capacitors**, into and out of different electrical configurations. Ideal switching elements (e.g., transistors operated outside of their active mode) have no resistance when "closed" and carry no current when "open", and so the converters can theoretically operate with 100% efficiency (i.e., all input power is delivered to the load; no power is wasted as dissipated heat).

For example, if a DC source, an inductor, a switch, and the corresponding **electrical ground** are placed in series and the switch is driven by a **square wave**, the peak-to-peak voltage of the waveform measured across the switch can exceed the input voltage from the DC source. This is because the inductor responds to changes in current by inducing its own voltage to counter the change in current, and this voltage adds to the source voltage while the switch is open. If a diode-and-capacitor combination is placed in parallel to the switch, the peak voltage can be stored in the capacitor, and the capacitor can be used as a DC source with an output voltage greater than the DC voltage driving the circuit. This **boost converter** acts like a **step-up transformer** for DC signals. A **buck–boost converter** works in a similar manner, but yields an output voltage which is opposite in polarity to the input voltage. Other buck circuits exist to boost the average output current with a reduction of voltage.

In an SMPS, the output current flow depends on the input power signal, the storage elements and circuit topologies used, and also on the pattern used (e.g., **pulse-width modulation** with an adjustable **duty cycle**) to drive the switching elements. Typically, the **spectral density** of these switching waveforms has energy concentrated at relatively high frequencies. As such, switching transients, like **ripple**, introduced onto the output waveforms can be filtered with small **LC filters**.



Advantages and disadvantages

[\[edit\]](#)

The main advantage of this method is greater efficiency because the switching transistor dissipates little power when it is outside of its active region (i.e., when the transistor acts like a switch and either has a negligible voltage drop across it or a negligible current through it). Other advantages include smaller size and lighter weight (from the elimination of low frequency transformers which have a high weight) and lower heat generation due to higher efficiency. Disadvantages include greater complexity, the generation of high-amplitude, high-frequency energy that the low-pass filter must block to avoid [electromagnetic interference](#) (EMI), and a [ripple voltage](#) at the switching frequency and the [harmonic frequencies](#) thereof.

Very low cost SMPSs may couple electrical switching noise back onto the mains power line, causing interference with A/V equipment connected to the same phase. Non-[power-factor-corrected](#) SMPSs also cause harmonic distortion.

Classification

[\[edit\]](#)

SMPSs can be classified into four types according to the input and output waveforms:

- AC in, DC out: [rectifier](#), off-line converter input stage
- DC in, DC out: [voltage converter](#), or current converter, or [DC to DC converter](#)
- AC in, AC out: [frequency changer](#), [cycloconverter](#), transformer, [phase converter](#)
- DC in, AC out: [inverter](#)

SMPS and linear power supply comparison

[\[edit\]](#)

There are two main types of regulated power supplies available: SMPS and linear. The following table compares linear regulated and unregulated AC-to-DC supplies with switching regulators in general:

Comparison of a linear power supply and a switched-mode power supply

	Linear power supply	Switching power supply	Notes
Size and weight	Heatsinks for high power linear regulators add size and weight. Transformers, if used, are large due to low operating frequency (mains power frequency is at 50 or 60 Hz); otherwise can be compact due to low component count.	Smaller transformer (if used; else inductor) due to higher operating frequency (typically 50 kHz – 1 MHz). Size and weight of adequate RF shielding may be significant.	A transformer's power handling capacity of given size and weight increases with frequency provided that hysteresis losses can be kept down. Therefore, higher operating frequency means either higher capacity or smaller transformer.
Output	With transformer used, any voltages available; if transformerless,	Any voltages available, limited only by transistor	A SMPS can usually cope with wider

voltage	not exceeding input. If unregulated, voltage varies significantly with load.	breakdown voltages in many circuits. Voltage varies little with load.	variation of input before the output voltage changes.
Efficiency, heat, and power dissipation	If regulated: efficiency largely depends on voltage difference between input and output; output voltage is regulated by dissipating excess power as heat resulting in a typical efficiency of 30–40%. ^[1] If unregulated, transformer iron and copper losses may be the only significant sources of inefficiency.	Output is regulated using duty cycle control; the transistors are switched fully on or fully off, so very little resistive losses between input and the load. The only heat generated is in the non-ideal aspects of the components and quiescent current in the control circuitry.	Switching losses in the transistors (especially in the short part of each cycle when the device is partially on), on-resistance of the switching transistors, equivalent series resistance in the inductor and capacitors, and core losses in the inductor, and rectifier voltage drop contribute to a typical efficiency of 60–70%. However, by optimizing SMPS design (such as choosing the optimal switching frequency, avoiding saturation of inductors, and active rectification), the amount of power loss and heat can be minimized; a good design can have an efficiency of 95%.
Complexity	Unregulated may be simply a diode and capacitor; regulated has a voltage-regulating circuit and a noise-filtering capacitor; usually a simpler circuit (and simpler feedback loop stability criteria) than switched-mode circuits.	Consists of a controller IC, one or several power transistors and diodes as well as a power transformer, inductors, and filter capacitors . Some design complexities present (reducing noise/interference; extra limitations on maximum ratings of transistors at high switching speeds) not found in linear regulator circuits.	In switched-mode mains (AC-to-DC) supplies, multiple voltages can be generated by one transformer core, but that can introduce design/use complications: for example it may place *minimum* output current restrictions on one output. For this SMPSs have to use duty cycle control. One of the outputs has to be chosen to feed the voltage regulation feedback loop (Usually 3.3 V or 5 V loads are more fussy about their supply voltages than the 12 V loads, so this drives the decision as to which feeds the feedback loop. The other outputs usually track the regulated one pretty well). Both need a careful selection of their transformers. Due to the high operating frequencies in SMPSs, the stray inductance and capacitance of the printed circuit board traces become important.
	Mild high-frequency interference may		

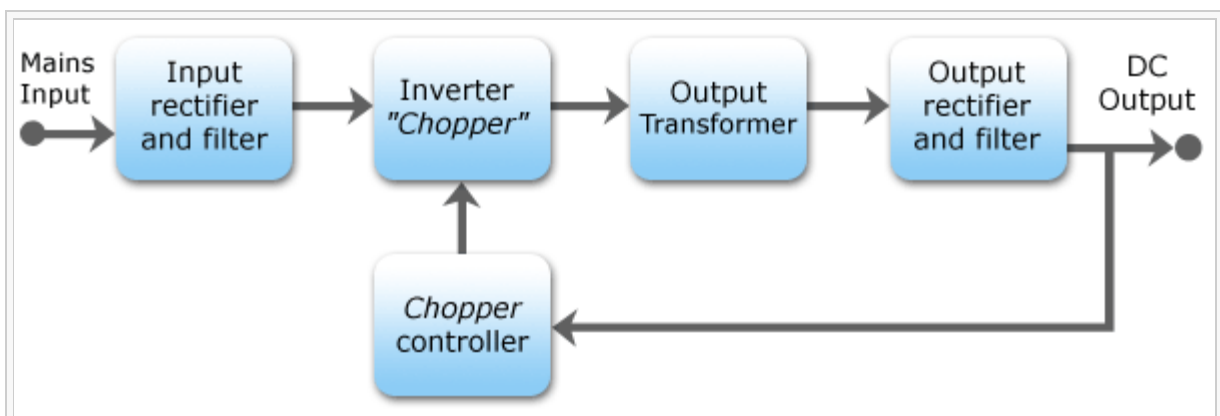
Radio frequency interference	<p>be generated by AC rectifier diodes under heavy current loading, while most other supply types produce no high-frequency interference. Some mains hum induction into unshielded cables, problematical for low-signal audio.</p>	<p>EMI/RFI produced due to the current being switched on and off sharply. Therefore, EMI filters and RF shielding are needed to reduce the disruptive interference.</p>	<p>Long wires between the components may reduce the high frequency filter efficiency provided by the capacitors at the inlet and outlet. Stable switching frequency may be important.</p>
Electronic noise at the output terminals	<p>Unregulated PSUs may have a little AC ripple superimposed upon the DC component at twice mains frequency (100–120 Hz). Can cause audible mains hum in audio equipment or brightness ripples or banded distortions in analog security cameras.</p>	<p>Noisier due to the switching frequency of the SMPS. An unfiltered output may cause glitches in digital circuits or noise in audio circuits.</p>	<p>This can be suppressed with capacitors and other filtering circuitry in the output stage. With a switched mode PSU the switching frequency can be chosen to keep the noise out of the circuits working frequency band (e.g., for audio systems above the range of human hearing)</p>
Electronic noise at the input terminals	<p>Causes harmonic distortion to the input AC, but relatively little or no high frequency noise.</p>	<p>Very low cost SMPS may couple electrical switching noise back onto the mains power line, causing interference with A/V equipment connected to the same phase. Non power-factor-corrected SMPSs also cause harmonic distortion.</p>	<p>This can be prevented if a (properly earthed) EMI/RFI filter is connected between the input terminals and the bridge rectifier.</p>
Acoustic noise	<p>Faint, usually inaudible mains hum, usually due to vibration of windings in the</p>	<p>Usually inaudible to most humans, unless they have a fan or are unloaded/malfunctioning, or use a switching frequency within the</p>	<p>The operating frequency of an unloaded SMPS is sometimes in the audible human range, and may sound subjectively quite loud for people who</p>

		transformer and/or magnetostriction .	audio range, or the laminations of the coil vibrate at a subharmonic of the operating frequency.	have hyperacusis in the relevant frequency range.
	Power factor	Low for a regulated supply because current is drawn from the mains at the peaks of the voltage sinusoid , unless a choke-input or resistor-input circuit follows the rectifier (now rare).	Ranging from very low to medium since a simple SMPS without PFC draws current spikes at the peaks of the AC sinusoid.	Active/passive power factor correction in the SMPS can offset this problem and are even required by some electric regulation authorities, particularly in Europe. The internal resistance of low-power transformers in linear power supplies usually limits the peak current each cycle and thus gives a better power factor than many switched-mode power supplies that directly rectify the mains with little series resistance.
	Inrush current	Large current when mains-powered linear power supply equipment is switched on until magnetic flux of transformer stabilises and capacitors charge completely, unless a slow-start circuit is used.	Extremely large peak "in-rush" surge current limited only by the impedance of the input supply and any series resistance to the filter capacitors.	Empty filter capacitors initially draw large amounts of current as they charge up, with larger capacitors drawing larger amounts of peak current. Being many times above the normal operating current, this greatly stresses components subject to the surge, complicates fuse selection to avoid nuisance blowing and may cause problems with equipment employing overcurrent protection such as uninterruptible power supplies . Mitigated by use of a suitable soft-start circuit or series resistor.
	Risk of electric shock	Supplies with transformers allow metalwork to be grounded, safely. Dangerous if primary/secondary insulation breaks down, unlikely with reasonable design. Transformerless mains-operated supply dangerous. In both linear and SM the mains, and possibly the output voltages,	Common rail of equipment (including casing) is energised to half mains voltage, but at high impedance, unless equipment is earthed/grounded or doesn't contain EMI/RFI filtering at the input terminals.	Due to regulations concerning EMI/RFI radiation, many SMPS contain EMI/RFI filtering at the input stage before the bridge rectifier consisting of capacitors and inductors. Two capacitors are connected in series with the Live and Neutral rails with the Earth connection in between the two capacitors. This forms a capacitive divider that energises the common rail at half mains voltage. Its high impedance current source can provide a tingling or a 'bite' to the operator or can be exploited to light an Earth Fault LED. However, this current may cause nuisance tripping on the most sensitive residual-current devices .

	are hazardous and must be well-isolated.		
Risk of equipment damage	Very low, unless a short occurs between the primary and secondary windings or the regulator fails by shorting internally.	Can fail so as to make output voltage very high. Stress on capacitors may cause them to explode. Can in some cases destroy input stages in amplifiers if floating voltage exceeds transistor base-emitter breakdown voltage, causing the transistor's gain to drop and noise levels to increase. ^[2] Mitigated by good failsafe design. Failure of a component in the SMPS itself can cause further damage to other PSU components; can be difficult to troubleshoot.	The floating voltage is caused by capacitors bridging the primary and secondary sides of the power supply. A connection to an earthed equipment will cause a momentary (and potentially destructive) spike in current at the connector as the voltage at the secondary side of the capacitor equalises to earth potential.

Theory of operation

[\[edit\]](#)

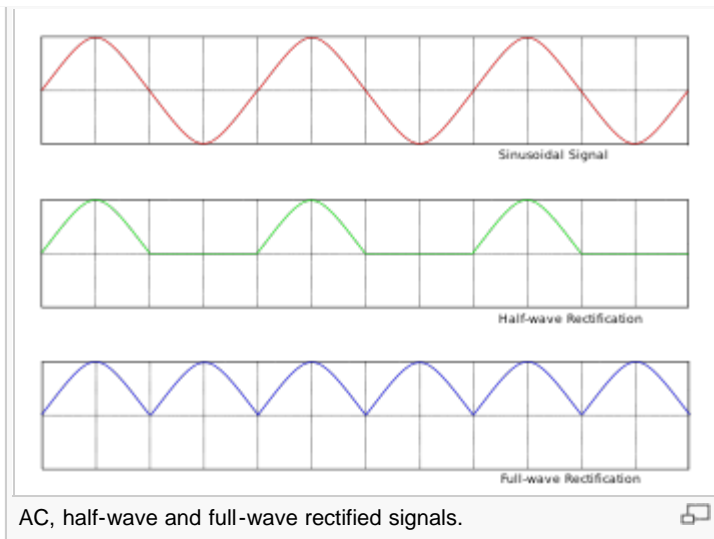


Block diagram of a mains operated AC–DC SMPS with output voltage regulation

Input rectifier stage

[\[edit\]](#)

If the SMPS has an AC input, then the first stage is to convert the input to DC. This is called *rectification*. The rectifier circuit can be configured as a voltage doubler by the addition of a switch operated either manually or automatically. This is a feature of larger supplies to permit operation from nominally 120 V or 240 V



supplies. The rectifier produces an unregulated DC voltage which is then sent to a large filter capacitor. The current drawn from the mains supply by this rectifier circuit occurs in short pulses around the AC voltage peaks.

These pulses have significant high

frequency energy which reduces the power factor. Special control techniques can be employed by the following SMPS to force the average input current to follow the sinusoidal shape of the AC input voltage thus the designer should try correcting the power factor. An SMPS with a DC input does not require this stage. An SMPS designed for AC input can often be run from a DC supply (for 230 V AC this would be 330 V DC), as the DC passes through the rectifier stage unchanged. It's however advisable to consult the manual before trying this, though most supplies are quite capable of such operation even though nothing is mentioned in the documentation. However, this type of use may be harmful to the rectifier stage as it will only use half of diodes in the rectifier for the full load. This may result in overheating of these components, and cause them to fail prematurely. ^[3]

If an input range switch is used, the rectifier stage is usually configured to operate as a [voltage doubler](#) when operating on the low voltage (~120 V AC) range and as a straight rectifier when operating on the high voltage (~240 V AC) range. If an input range switch is not used, then a full-wave rectifier is usually used and the downstream inverter stage is simply designed to be flexible enough to accept the wide range of DC voltages that will be produced by the rectifier stage. In higher-power SMPSs, some form of automatic range switching may be used.

Inverter stage [edit]

This section refers to the block marked *chopper* in the block diagram.

The inverter stage converts DC, whether directly from the input or from the rectifier stage described above, to AC by running it through a power oscillator, whose output transformer is very small with few windings at a frequency of tens or hundreds of [kilohertz](#) (kHz). The frequency is usually chosen to be above 20 kHz, to make it inaudible to humans. The output voltage is optically coupled to the input and thus very tightly controlled. The switching is implemented as a multistage (to achieve high gain) [MOSFET](#) amplifier. MOSFETs are a type of [transistor](#) with a low on-[resistance](#) and a high current-handling capacity.

Voltage converter and output rectifier [edit]

If the output is required to be isolated from the input, as is usually the case in mains power supplies, the inverted AC is used to drive the primary winding of a high-frequency [transformer](#). This converts the voltage up or down to the required output level on its secondary winding. The output transformer in the block diagram serves this purpose.

If a DC output is required, the AC output from the transformer is rectified. For output voltages above ten volts or so, ordinary silicon diodes are commonly used. For lower voltages, [Schottky diodes](#) are commonly used as the rectifier elements; they have the advantages of faster recovery times than

silicon diodes (allowing low-loss operation at higher frequencies) and a lower voltage drop when conducting. For even lower output voltages, MOSFETs may be used as [synchronous rectifiers](#); compared to Schottky diodes, these have even lower conducting state voltage drops.

The rectified output is then smoothed by a filter consisting of [inductors](#) and [capacitors](#). For higher switching frequencies, components with lower capacitance and inductance are needed.

Simpler, non-isolated power supplies contain an inductor instead of a transformer. This type includes [boost converters](#), [buck converters](#), and the [buck-boost converters](#). These belong to the simplest class of single input, single output converters which use one inductor and one active switch. The buck converter reduces the input voltage in direct proportion to the ratio of conductive time to the total switching period, called the duty cycle. For example an ideal buck converter with a 10 V input operating at a 50% duty cycle will produce an average output voltage of 5 V. A feedback control loop is employed to regulate the output voltage by varying the duty cycle to compensate for variations in input voltage. The output voltage of a [boost converter](#) is always greater than the input voltage and the buck-boost output voltage is inverted but can be greater than, equal to, or less than the magnitude of its input voltage. There are many variations and extensions to this class of converters but these three form the basis of almost all isolated and non-isolated DC to DC converters. By adding a second inductor the [Ćuk](#) and [SEPIC](#) converters can be implemented, or, by adding additional active switches, various bridge converters can be realised.

Other types of SMPSs use a [capacitor-diode voltage multiplier](#) instead of inductors and transformers. These are mostly used for generating high voltages at low currents (*Cockcroft-Walton generator*). The low voltage variant is called [charge pump](#).

Regulation

[\[edit\]](#)

A [feedback](#) circuit monitors the output voltage and compares it with a reference voltage, which shown in the block diagram serves this purpose. Depending on design/safety requirements, the controller may contain an isolation mechanism (such as [opto-couplers](#)) to isolate it from the DC output. Switching supplies in computers, TVs and VCRs have these opto-couplers to tightly control the output voltage.

Open-loop regulators do not have a feedback circuit. Instead, they rely on feeding a constant voltage to the input of the transformer or inductor, and assume that the output will be correct. Regulated designs compensate for the [impedance](#) of the transformer or coil. Monopolar designs also compensate for the [magnetic hysteresis](#) of the core.

The feedback circuit needs power to run before it can generate power, so an additional non-switching power-supply for stand-by is added.

Transformer design

[\[edit\]](#)

SMPS transformers run at high frequency. Most of the cost savings (and space savings) in off-line power supplies come from the fact that a high frequency transformer is much smaller than the 50/60 Hz transformers formerly used. There are additional design tradeoffs.

Transformer size

[\[edit\]](#)

The higher the switching frequency, the lower the amount of energy that needs to be stored intermediately during the time of a single switching cycle. Because this energy is stored in form of magnetic energy in the transformer core material (like [ferrite](#)), less of such material is needed.

However, higher frequency also means more energy lost during transitions of the switching semiconductor. Furthermore, much more attention to the physical layout of the [circuit board](#) is required, and the amount of [electromagnetic interference](#) will be more pronounced.

[\[edit\]](#)

Core loss

There are several differences in the design of transformers for 50 Hz vs 500 kHz. Firstly a low frequency transformer usually transfers energy through its core (soft iron), while the (usually ferrite) core of a high frequency transformer limits leakage.

Copper loss

[\[edit\]](#)

Main article: [Copper loss](#)

At low frequencies (such as the line frequency of 50 or 60 Hz), designers can usually ignore the [skin effect](#). At line frequencies, the skin effect becomes important when the conductors have a diameter larger than about 0.3 inches (7.6 mm).

Switching power supplies must pay more attention to the skin effect because it is a source of power loss. At 500 kHz, the skin depth is about 0.003 inches (0.076 mm) – a dimension smaller than the typical wires used in a power supply.

The skin effect is exacerbated by the harmonics present in the switching waveforms. The appropriate skin depth is not just the depth at the fundamental, but also the skin depths at the harmonics.^[4]

Since the waveforms in a SMPS are generally high speed (PWM square waves), the wiring must be capable of supporting high harmonics of the base frequency due to [skin effect](#).

In addition to the skin effect, there is also a [proximity effect](#), which is another source of power loss.

Power factor

[\[edit\]](#)

Main article: [power factor](#)

Simple off-line switched mode power supplies incorporate a simple full wave rectifier connected to a large energy storing capacitor. Such SMPSs draw current from the AC line in short pulses when the mains instantaneous voltage exceeds the voltage across this capacitor. During the remaining portion of the AC cycle the capacitor provides energy to the power supply.

As a result, the input current of such basic switched mode power supplies has high [harmonic](#) content and relatively low [power factor](#). This creates extra load on utility lines, increases heating of the utility [transformers](#) and standard AC electric motors, and may cause stability problems in some applications such as in emergency generator systems or aircraft generators. Harmonics can be removed through the use of filter banks but the filtering is expensive, and the power utility may require a business with a very low power factor to purchase and install the filtering onsite.

Unlike displacement power factor created by linear inductive or capacitive loads, this distortion cannot be corrected by addition of a single linear component. Additional circuits are required to counteract the effect of the brief current pulses.

In 2001, the European Union put into effect the standard IEC/EN61000-3-2 to set limits on the harmonics of the AC input current up to the 40th harmonic for equipment above 75 W. The standard defines four classes of equipment depending on its type and current waveform. The most rigorous limits (class D) are established for personal computers, computer monitors, and TV receivers. In order to comply with these requirements modern switched-mode power supplies normally include an additional [power factor correction](#) (PFC) stage.

Putting a current regulated boost chopper stage after the off-line rectifier (to charge the storage capacitor) can correct the power factor, but increases the complexity (and any cost).

Types

[\[edit\]](#)

Switched-mode power supplies can be classified according to the circuit topology. The most important distinction is between isolated converters and non-isolated ones.

Non-isolated topologies

[\[edit\]](#)

Non-isolated converters are simplest, with the three basic types using a single inductor for energy storage. In the voltage relation column, D is the duty cycle of the converter, and can vary from 0 to 1. V_{in} is assumed to be greater than zero; if it is negative, negate V_{out} to match.

Type ^[5]	Power [W]	Typical efficiency	Relative cost	Energy storage	Voltage relation	Features
Buck	0–1,000	80–90%	1.0	Single inductor	$0 \leq \text{Out} \leq \text{In}$, $V_2 = DV_1$	Current is continuous at output.
Boost	0–150	70%	1.0	Single inductor	$\text{Out} \geq \text{In}$, $V_2 = \frac{1}{1-D} V_1$	Current is continuous at input.
Buck-boost	0–150	78%	1.0	Single inductor	$\text{Out} \leq 0$, $V_2 = -\frac{D}{1-D} V_1$	Current is dis-continuous at both input and output.
Split-pi (or, boost-buck)	0–4,500	96%	>2.0	Two inductors and three capacitors	Up or down	Bidirectional power control; in or out
Ćuk				Capacitor and two inductors	Any inverted, $V_2 = -\frac{D}{1-D} V_1$	Current is continuous at input <i>and</i> output
SEPIC				Capacitor and two inductors	Any, $V_2 = \frac{D}{1-D} V_1$	Current is continuous at input
Zeta				Capacitor and two inductors	Any, $V_2 = \frac{D}{1-D} V_1$	Current is continuous at output
Charge pump				Capacitors only		Low performance. Like a CW multiplier, the disadvantages of charge pumps for power conversion can be somewhat mitigated through proper component sizing and drive frequency, since output energy is proportional to capacitance and frequency.

When equipment is human-accessible, voltage and power limits of ≤ 42.4 V peak/60 V dc and 250 VA apply for Safety Certification ([UL](#), [CSA](#), [VDE](#) approval).

The buck, boost, and buck-boost topologies are all strongly related. Input, output and ground come together at one point. One of the three passes through an inductor on the way, while the other two pass through switches. One of the two switches must be active (e.g., a transistor), while the other can be a diode. Sometimes, the topology can be changed simply by re-labeling the connections. A 12 V input, 5 V output buck converter can be converted to a 7 V input, −5 V output buck-boost by grounding the *output* and taking the output from the *ground* pin.

Likewise, SEPIC and Zeta converters are both minor rearrangements of the Ćuk converter.

Switchers become less efficient as duty cycles become extremely short. For large voltage changes, a transformer (isolated) topology may be better.

Isolated topologies

[\[edit\]](#)

All isolated topologies include a **transformer**, and thus can produce an output of higher or lower voltage than the input by adjusting the turns ratio.^{[6][7]} For some topologies, multiple windings can be placed on the transformer to produce multiple output voltages.^[8] Some converters use the transformer for energy storage, while others use a separate inductor.

Type ^[5]	Power [W]	Typical efficiency	Relative cost	Input range [V]	Energy storage	Features
Flyback	0–250	78%	1.0	5–600	Transformer	Isolated form of the buck-boost converter. ¹
Ringing choke converter (RCC)	0–150	78%	1.0	5–600	Transformer	Low-cost self-oscillating flyback variant. ^[9]
Half-forward	0–250	75%	1.2	5–500	Inductor	
Forward ²	100–200	78%		60–200	Inductor	Isolated form of buck converter
Resonant forward	0–60	87%	1.0	60–400	Inductor and capacitor	Single rail input, unregulated output, high efficiency, low EMI. ^[10]
Push-pull	100–1,000	72%	1.75	50–1,000	Inductor	
Half-bridge	0–2,000	72%	1.9	50–1,000	Inductor	
Full-bridge	400–5,000	69%	>2.0	50–1,000	Inductor	Very efficient use of transformer, used for highest powers.
Resonant, zero voltage switched	>1,000		>2.0			
Isolated Ćuk					Two capacitors and two inductors	

- ^{^1} Flyback converter logarithmic control loop behaviour might be harder to control than other types.^[11]
- ^{^2} The forward converter has several variants, varying in how the transformer is "reset" to zero **magnetic flux** every cycle.

Quasi-resonant zero-current/zero-voltage switch

[\[edit\]](#)

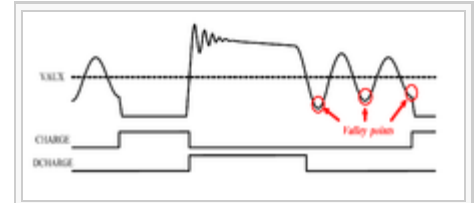
A quasi-resonant zero-current/zero-voltage switch (ZCS/ZVS) where "each switch cycle delivers a quantized 'packet' of energy to the converter output, and switch turn-on and turn-off occurs at zero current and voltage, resulting in an essentially lossless switch."^[12] Quasi-resonant switching, also known as *valley switching*, reduces **EMI** in the power supply by two



Zero voltage switched power supplies require only small heatsinks as little energy is lost as heat. This allows them to be small. This ZVS can deliver more than 1 kilowatt. Transformer is not shown.

methods:

1. By switching the bipolar switch when the voltage is at a minimum (in the valley) to minimize the hard switching effect that causes EMI.
2. By switching when a valley is detected, rather than at a fixed frequency, introduces a natural frequency jitter that spreads the RF emissions spectrum and reduces overall EMI.



Quasi-resonant switching switches when the voltage is at a minimum and a valley is detected

Efficiency and EMI

[[edit](#)]

Higher input voltage and synchronous rectification mode makes the conversion process more efficient; the power consumption of the controller also has to be taken into account. Higher switch frequency allows component sizes to be shrunk, but can produce more [radio frequency](#) (RF) interference. A resonant forward converter produces the lowest [EMI](#) of any SMPS approach because it uses a soft-switching [resonant](#) waveform compared with conventional hard switching.

Failure modes

[[edit](#)]

Power supplies which use capacitors suffering from the [capacitor plague](#) may experience premature failure when the capacitance drops to 4% of the original value. This usually causes the switching semiconductor to fail in a conductive way. That may expose connected loads to the full input volt and current, and precipitate wild oscillations in output.^[13]

Failure of the switching transistor is common. Due to the large switching voltages this transistor must handle (around 325 V for a 230 V_{AC} mains supply), these transistors often short out, in turn immediately blowing the main internal power fuse.

For failure in switching components, circuit board etc.. read the [failure modes of electronics](#) article.

Precautions

[[edit](#)]

The main filter capacitor will often store up to 325 V long after the power cord has been removed from the wall. Not all power supplies contain a small "bleeder" resistor to slowly discharge this capacitor. Any contact with this capacitor may result in a severe electrical shock.

The primary and secondary side may be connected with a capacitor to reduce [EMI](#) and compensate for various capacitive couplings in the converter circuit, where the transformer is one. This may result in electric shock in some cases. The current flowing from [line](#) or [neutral](#) through a 2000 Ω resistor to any accessible part must according to IEC 60950 be less than 250 μA for IT equipment.^[14]

Applications

[[edit](#)]

Main article: [Switched-mode power supply applications](#)

Switched-mode power supply units (PSUs) in domestic products such as [personal computers](#) often have universal inputs, meaning that they can accept power from [mains supplies](#) throughout the world, although a manual voltage range switch may be required. Switch-mode power supplies can tolerate a wide range of [power frequencies](#).

In 2006, at an [Intel Developers Forum](#), Google engineers proposed the use of a single 12 V supply inside PCs, due to the high efficiency of switch mode supplies directly on the PCB.^[15]



Switched mode mobile phone charger

Due to their high volumes [mobile phone chargers](#) have always been particularly cost sensitive. The first chargers were [linear power supplies](#) but they quickly moved to the cost effective ringing choke converter (RCC) SMPS topology, when new levels of efficiency were required. Recently the demand for even lower no load power requirements in the application has meant that flyback topology is being used more widely; primary side sensing flyback controllers are also helping to cut the [bill of materials](#) (BOM) by removing secondary-side sensing components such as [optocouplers](#).

Where integration of capacitors for stabilization and batteries as a energy storage or hum and interference needs to be avoided in the power distribution, SMPS may be essential for efficient conversion of electric DC energy. For AC applications where frequency and voltage can't be produced by the primary source an SMPS may be essential as well. Applications may be found in the automobile industry where ordinary trucks uses nominal $24 V_{DC}$ but may need $12 V_{DC}$. Ordinary cars use nominal $12 V_{DC}$ and may need to convert this to drive equipment. In industrial settings, DC supply is sometimes chosen to avoid hum and interference and ease the integration of capacitors and batteries used to buffer the voltage that makes SMPS essential.

Terminology

[[edit](#)]

The term switchmode was widely used until [Motorola](#) claimed ownership of (but did not register^[16]) the trademark SWITCHMODE, for products aimed at the switching-mode power supply market, and started to enforce their trademark.^[17] *Switching-mode power supply*, *switching power supply*, and *switching regulator* refer to this type of power supply.^[17]

See also

[[edit](#)]

- [Autotransformer](#)
- [Boost converter](#) can be seen as analogous to a [hydraulic ram](#), using the [electronic–hydraulic analogy](#)^[18]
- [Conducted Electromagnetic Interference](#)
- [DC to DC converter](#)
- [Joule thief](#)
- [Leakage inductance](#)
- [Switching amplifier](#)
- [Transformer](#)
- [Vibrator \(electronic\)](#)
- [Inrush current](#)



Notes

[[edit](#)]

- ^{1.} ↑ "[Energy Savings Opportunity by Increasing Power Supply Efficiency](#)" ↗.
- ^{2.} ↑ "[Ban Looms for External Transformers](#)" ↗. 080224 sound.westhost.com
- ^{3.} ↑ "[DC Power Production, Delivery and Utilization, An EPRI White Paper](#)" ↗ (PDF). Page 9 080317 mydocs.epri.com
- ^{4.} ↑ Pressman's book ^{[a](#)} ^{[b](#)}
- ↗ applications
- ^{11.} ↑ "[Gain Equalization Improves Flyback Performance Page of](#)" ↗. 100517 powerelectronics.com
- ^{12.} ↑ EDN: [Comparing DC/DC converters' noise-related performance](#) ↗
- ^{13.} ↑ "[Bad Capacitors: Information and symptoms](#)" ↗. 100211 lowyat.net



A 450 Watt SMPS for use in [personal computers](#) with the power input, fan, and output cords visible ↗

5. [^] ON Semiconductor (July 11, 2002). "SWITCHMODE Power Supplies—Reference Manual and Design Guide" (PDF). Retrieved 2008-11-11.^[*dead link*]
6. [^] "DC-DC Converter Basics" . 090112 powerdesigners.com
7. [^] "DC-DC CONVERTERS: A PRIMER" . 090112 jaycar.com.au Page 4
8. [^] http://schmidt-walter.eit.h-da.de/snt/snt_eng/snte_pdf.html
9. [^] Irving, Brian T.; Jovanović, Milan M. (March 2002), *Analysis and Design of Self-Oscillating Flyback Converter* , Proc. IEEE Applied Power Electronics Conf. (APEC), pp. 897–903, retrieved 2009-09-30
10. [^] "RDFC topology for linear replacement" . 090725 camsemi.com Further information on resonant forward topology for consumer
11. [^] "Model Synthesis for Design of Switched Systems Using a Variable Structure System Formulation", Javier A. Kypuros and Raul G. Longoria, J. Dyn. Sys., Meas., Control 125, 618 (2003), DOI:10.1115/1.1636774, [1]
12. [^] "High-efficiency power supplies for home computers and servers" .
13. [^] "Electrical Power Quality and Utilisation, Journal Vol. XV, No. 2, 2009: Estimation of Optimum Value of Y-Capacitor for Reducing Emi in Switch Mode Power Supplies"
14. [^] "United States Patent and Trademark Office" United States Patent and Trademark Office (trademark search for "SWITCHMODE"). Retrieved 2009-12-13.
15. [^] ^a ^b Foutz, Jerrold. "Switching-Mode Power Supply Design Tutorial Introduction" . Retrieved 2008-10-06.

References

[[edit](#)]

- Basso, Christophe (2008), *Switch-Mode Power Supplies: SPICE Simulations and Practical Designs*, McGraw-Hill, ISBN 0071508589
- Brown, Marty (2001), *Power Supply Cookbook* (2nd ed.), Newnes, ISBN 0-7506-7329-X
- Erickson, Robert W.; Maksimovic, Dragan (2001), *Fundamentals of Power Electronics* (Second ed.), ISBN 0-7923-7270-0
- Liu, Mingliang (2006), *Demystifying Switched-Capacitor Circuits*, Elsevier, ISBN 0-7506-7907-7
- Luo, Fang Lin; Ye, Hong (2004), *Advanced DC/DC Converters*, CRC Press, ISBN 0-8493-1956-0
- Luo, Fang Lin; Ye, Hong; Rashid, Muhammad H. (2005), *Power Digital Power Electronics and Applications*, Elsevier, ISBN 0-12-088757-6
- Maniktala, Sanjaya (2004), *Switching Power Supply Design and Optimization*, McGraw-Hill, ISBN 0071434836
- Maniktala, Sanjaya (2006), *Switching Power Supplies A to Z*, Newnes/Elsevier, ISBN 0750679700
- Maniktala, Sanjaya (2007), *Troubleshooting Switching Power Converters: A Hands-on Guide*, Newnes/Elsevier, ISBN 0750684216
- Mohan, Ned; Undeland, Tore M.; Robbins, William P. (2002), *Power Electronics : Converters, Applications, and Design*, Wiley, ISBN 0-471-22693-9
- Nelson, Carl (1986), *LT1070 design Manual* , **AN19**, Linear Technology Application Note giving an extensive introduction in Buck, Boost, CUK, Inverter applications. (download as PDF from http://www.linear.com/designtools/app_notes.php)
- Pressman, Abraham I.; Billings, Keith; Morey, Taylor (2009), *Switching Power Supply Design* (Third ed.), McGraw-Hill, ISBN 0-07-148272-5
- Rashid, Muhammad H. (2003), *Power Electronics: Circuits, Devices, and Applications*, Prentice Hall, ISBN 0-13-122815-3

External links

[[edit](#)]

- [Switching-Mode Power Supply Design](#)
- [Unitrode Power Supply Design Seminar Books Online](#)
- [95% Efficiency Switching Power Supply design, PSpice simulation](#)
-



[A general description of DC-DC converters](#)

- [Online Power Supplies manufacturers database](#)
- [Switching Power Supply, switch-mode supplies](#)
- [AN25 - Switching Regulators For Poets: A Gentle Guide For the Trepidatious](#), Jim Williams, Linear Technology Corporation
- [DC-DC Converter Tutorial](#) This article outlines the different types of switching regulators used in DC-DC conversion.
- [Introduction to power supplies](#) – National Semiconductor
- [Compendium and database of power supply efficiency regulations](#)
- [Power Supplies industry press releases, jobs, design discussions](#)
- [SMPS Topologies Poster from TI](#)
- [A useful Web calculator and theory text for various SMPS topologies](#)
- [Switching mode power supply's principle of operation and current formula.](#)

View page ratings

Rate this page

[What's this?](#)

Trustworthy

Objective

Complete

Well-written

I am highly knowledgeable about this topic (optional)

I have a relevant college/university degree

It is part of my profession

It is a deep personal passion

The source of my knowledge is not listed here

I would like to help improve Wikipedia, send me an e-mail (optional)

We will send you a confirmation e-mail. We will not share your address with anyone. ([Privacy policy](#))

Saved successfully

Your ratings have not been submitted yet

Your ratings have expired

Please reevaluate this page and submit new ratings.

An error has occurred. Please try again later.

Thanks! Your ratings have been saved.

Please take a moment to complete a short survey.

Thanks! Your ratings have been saved.

Do you want to create an account?

An account will help you track your edits, get involved in discussions, and be a part of the community.

or

Thanks! Your ratings have been saved.

Did you know that you can edit this page?

Categories: [Power supplies](#) | [Power electronics](#) | [Electrical power conversion](#)

Text is available under the [Creative Commons Attribution-ShareAlike License](#); additional terms may apply. See [Terms of use](#) for details.

Wikipedia® is a registered trademark of the [Wikimedia Foundation, Inc.](#), a non-profit organization.

[Contact us](#)

[Privacy policy](#) [About Wikipedia](#) [Disclaimers](#) [Mobile View](#)

