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//requires a 10k and 30k ohm voltage divider.
//capacitor is .1uF
// arduino is connected via a 220 ohm resistor to limit current while discharging capacitor
//the voltage output was off, but i believe the equation is right, so i modeled voltage out versus the
actual voltage in
// and it was a linear y=mx+b relationship.
// this may be due to resistor tolerances, but it could also be some other things.
//If you need this program for accurate measurements

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```

double arduinoVoltage = 4.94;

```

```

int digitalPin = 12;

```

```

void setup() {

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```

  Serial.begin(9600);
  delay(100);
  Serial.print("on");

```

```

}

```

```

void loop() {

```

```

  Serial.print("voltage: ");
  Serial.print(measureVolts(digitalPin));
  Serial.println("v");

```

```

}

```

```

double measureVolts(int pinNum){ //pinNum is the digital i/o pin

```

```

  double timeStart = 0;
  double timeEnd = 0;
  double timeMicroSec = 0;

```

```

  timeMicroSec = 0;
  pinMode(digitalPin, OUTPUT);
  digitalWrite(digitalPin, LOW);
  delay(2); //discharge the cap

```

```

  pinMode(digitalPin, INPUT);

```

```

  timeStart = micros(); // analogValuePrior = analogRead(Vpin);

```

```

  while(digitalRead(digitalPin) == LOW){} //wait for the pin to go HIGH

```

```

  timeEnd = micros(); // analogValueAfter = analogRead(Vpin);
  timeMicroSec = timeEnd - timeStart;

```

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  return convertToVolts(timeMicroSec);
}

```

```

double convertToVolts(double timeMicroSec){

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```

  double voltage = (2.5*pow(1.0013, timeMicroSec)/(pow(1.0013, timeMicroSec)-1))*4.0;
  return voltage;

```

```

//return (voltage + 4.744)/1.412; //this is the linear function fit. You shouldn't need this and if you
do, it will be different
}

```